TERRA ROVER: ENSURING SAFETY THROUGH ROBOTIC EXPLORATION

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College : Sri Siddhartha Institute Of Technology, Tumakuru
Branch : Department Of Electronics And Telecommunication Engineering
Guide(S) : Mr. Kevin
Student(S): Ms. Bushra Kousar
Mr. Farooq Ahmed Khan
Mr. Mohammed Saleem
Ms. Manasa

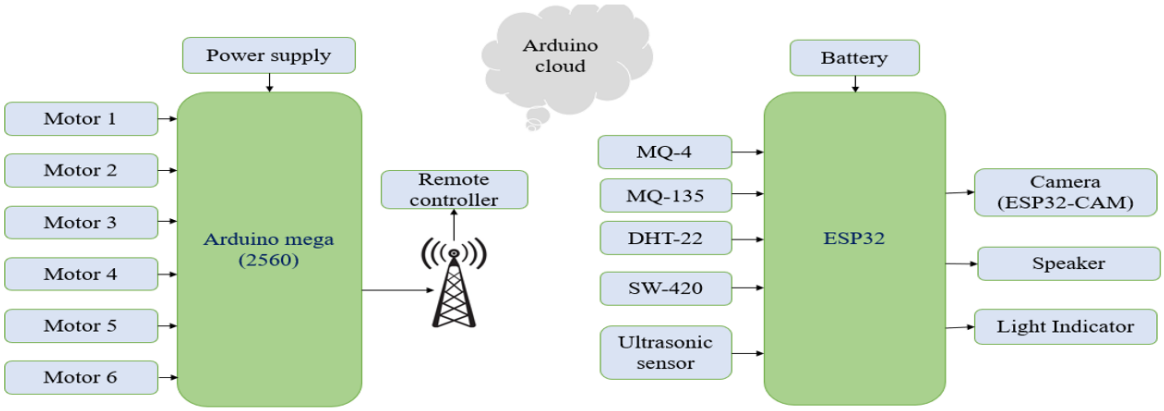
Keywords:

Safety robotics, wireless communication, gas detection, remote monitoring, terrain navigation, crack detection.

Introduction:

Coal mines are narrow tunnels with hazards like collapses, landslides, and dangerous gases (CO, CO_2, CH_4), which can cause explosions or poisoning. Methane, released during mining, spreads through the tunnels, creating significant risks for workers.

A mine-detecting rover with an MQ-4 gas sensor and a wireless camera will be



developed to identify gas leaks, navigate rugged terrains, and enhance safety.

Figure 1: Block diagram of terra rover.

Objectives:

- To design an efficient real-time monitoring system so that various leaked mine gases could be identified.
- To provide real-time data on gas concentrations, temperature and humidity to enable informed decision making.
- To give a inside view of mining caves and to provide a cost effective mine safety explorer**.**

Methodology:

The coal mine safety exploration rover follows a structured methodology to improve safety and emergency response during mining operations. Equipped with sensors such as gas detectors and water level sensors, the rover effectively identifies potential hazards like gas leaks, flooding, and structural risks. For navigation, it uses GPS technology to autonomously map the area and mark hazardous zones with a spray or paint mechanism, ensuring clear identification of unsafe locations.

To aid rescue efforts, the rover is designed to deliver essential supplies, including oxygen cylinders, food, water, oxygen masks, and first aid kits, to miners in distress. It also includes a failsafe feature to transmit its final coordinates in the event of a system failure or disaster, aiding recovery efforts. Real-time communication through Wi-Fi or LoRa ensures continuous updates and enables voice communication between the rover and rescue teams. Prior to deployment, the rover undergoes rigorous testing in controlled environments to validate its performance and reliability. This methodical approach ensures that the rover contributes effectively to mine safety and emergency preparedness.

Result and Conclusion:

The Terra Rover exemplifies how robotic exploration can significantly enhance safety in challenging and hazardous environments. By leveraging advanced sensors, autonomous navigation, and real-time data analysis, the rover reduces the need for human presence in dangerous terrains, thereby minimizing risk. Its design and capabilities underscore the growing importance of robotics in exploration, disaster

response, and environmental monitoring. As technology continues to evolve, platforms like the Terra Rover will play a pivotal role in ensuring safety, expanding our reach, and deepening our understanding of the world around us without compromising human lives.

Future Scope:

The future scope of this project includes:

1. The system will detect harmful gases like methane, carbon dioxide, and ammonia in the mine.
2. Early warnings will help prevent explosions and protect miners' health and safety.
3. It will monitor structural vibrations and identify cracks in the mine’s Infrastructure.
4. Timely alerts will allow preventive actions to avoid collapses and ensure stability.