VEHICLE IMPACT NOTIFICATION AND EMERGENCY CALLING

Project Reference No.: *47S_BE_2172*

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Keywords:

Vehicle Impact Detection,Emergency Call System,Arduino Microcontroller,GPS Tracking,Accelerometer Sensor,GSM Module (Optional),Cellular Network Communication (Optional),Real-Time Location Tracking ,Accident Notification Personal Safety

Introduction:

Traffic accidents are a growing concern, highlighting the need for faster emergency response. Existing tracking systems often focus on asset management, while dedicated emergency call systems require manual activation. This project tackles this challenge by creating a novel **vehicle impact notification and emergency calling system**. We leverage Arduino - a user-friendly microcontroller platform - coupled with GPS and accelerometer sensors to detect collisions and trigger automatic emergency calls (using a GSM module, optional) or notifications on a paired cellular phone. This potentially life-saving system aims to improve response times and outcomes for those involved in accidents. Existing vehicle tracking systems primarily focus on asset management, while dedicated emergency call systems often require manual activation. This project aims to develop a novel vehicle impact notification and emergency calling system utilizing Arduino-based hardware and software

Objectives:

- Design and build a system that detects vehicle collisions using an accelerometer sensor.
- Integrate GPS functionality to determine the real-time location of the accident scene.
- Implement an emergency call mechanism for automatic notification to designated emergency services (using a GSM module, optional).
- Alternatively, trigger an emergency call or SMS notification on a paired cellular phone in the car.
- Provide an optional local alert system using a buzzer or alarm to notify the driver and passengers upon impact detection

Methodology:

- The system will be built around an Arduino board (e.g., Uno or Nano) for data processing and code execution.
- A GPS module will be interfaced with the Arduino to acquire real-time location data (latitude and longitude).
- An accelerometer sensor will be integrated to detect changes in acceleration forces experienced by the vehicle during a potential collision.
- For automatic emergency call functionality, a GSM module with a cellular data plan will be included. The system will be programmed to transmit an emergency call with location data to a designated emergency response center upon impact detection.
- Alternatively, the system can be programmed to trigger an emergency call or SMS notification with location data to a pre-programmed number on a paired cellular phone in the car.
- An optional buzzer or alarm will be connected to the Arduino to provide a local alert within the vehicle upon collision detection.
- The code will be written in Arduino IDE, defining functionalities for sensor data acquisition, impact detection, location tracking, and emergency call initiation (or triggering a call on the paired phone).
- The system will be thoroughly tested under various driving conditions to ensure accurate impact detection, reliable location tracking, and successful emergency call triggering or notification.

Conclusion:

The project is expected to develop a functional vehicle impact notification and emergency calling system using Arduino technology. The system will potentially improve response times for emergency services in case of accidents, leading to better outcomes and potentially saving lives.

This is a proposed system, in which the model is a cost-effective, efficient, and very thorough.in their work. This type of research is used for reducing the number of incidents owing to the driver's use of accelerometer sensor, and in order to save people's lives with unexpected cases. For collecting the parameters of state drive and state, the proposed design has been implemented using different kinds of sensors in order to make any decisions, and to communicate the current location using the components, like, GSM and GPS modem.

This innovative and potentially life-saving system can significantly improve response times for emergency services, leading to better outcomes for accident victims. The project paves the way for further advancements in road safety through future work on sensor integration, user interfaces, and cloud connectivity.

Scope for future work:

- Integrating additional sensors (e.g., gyroscope) for more sophisticated collision detection algorithms.
- Implementing a user interface for system configuration and status monitoring.

- Exploring integration with cloud platforms for data storage and remote access.
- Investigating integration with existing emergency response systems for seamless data exchange.
- Conducting extensive field testing in real-world scenarios with emergency responders to assess effectiveness and refine the system.

This project establishes a foundation for an innovative vehicle impact notification and emergency calling system. Future work can further enhance its functionality and impact on improving road safety.